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# Programmable Automation Controller to manage 16/24 interpolated axes



## Power N 10.4" XGA

- TFT XGA display (1024x768) with touch screen
- 80-key thermoformed membrane keypad
- door for access to Ethernet, USB and CF memory
- mushroom-head emergency button
- electronic handwheel with axis selector and movement resolution selector (optional)
- overfeed potentiometers (optional)
- dimensions 434x400x160 (WxHxD in mm)



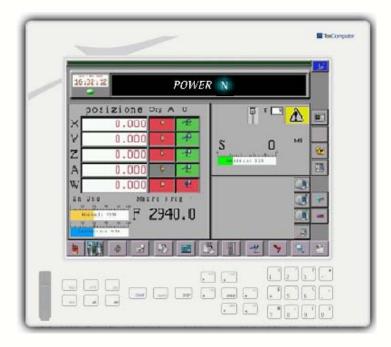
## Power N 15" - 80 keys

- TFT XGA 1024x768 pixel display with or without touch screen
- 80-key thermoformed membrane keypad
- door for access to CF
- mushroom-head emergency button
- dimensions 490x400x160 (WxHxD in mm)



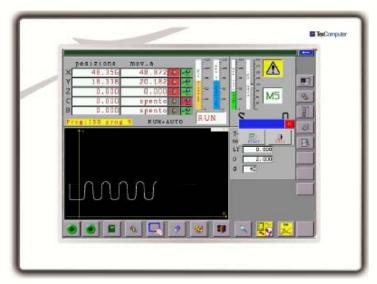


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## Power N 15" - 28 keys

- TFT XGA 1024x768 pixel display with touch screen
- 28-key thermoformed membrane keypad
- USB socket
- dimensions 400x355x160 (WxHxD in mm)



## Power N 15" - Only touch

- display TFT XGA (1024x768) with touch screen
- dimensions 398x296x100 WxHxD in mm)



## Fixed remotable terminal

- 10,4" WSVGA 1024x600 display with touch screen, dimensions 310x192x60 (WxHxD in mm)
- 15" XGA 1024x768 display with touch screen, 398x296x60 (WxHxD in mm)
- connection to Power N Box through 36-pole LVDS cable 10 m. long





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#### 10.4" Passive mobile terminal

- · ergonomic plastic case
- connection to Power N Box through 36-pole LVDS cable, 10 m. long
- TFT WSVGA 1024x600 pixel display with touch screen
- 4-key keypad
- dual-contact mushroom-head emergency button
- optional "dead man" button



## **Power N Box**

- · fixing from inside panel
- dimensions 300x240x160 (LxHxP in mm)







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## **Technical Data**

Description		Notes / Options
CPU	RISC 32 bit	264 MHz clock
Flash memory (F volume included)	8 MB	
Serial Flash memory	16 MB	Optional, can hold icons and character set
RAM memory (ritentive)	8 MB	
RAM memory (not ritentive)	4/8 MB	
Digital inputs 24 Vdc pnp - npn	44	
Protected outputs, 1 Amp. 24 Vdc pnp	32	
Configurable digital inputs / outputs	8	On I/O module inserted in slot P10
Analog inputs 010 V - 12 bit	8	On request: 4 may be 05V 4 may be 020mA
Analog inputs 05 volts - 12 bit	3	On on-board terminal board
Analog input +/-10 volts	1	On on-board terminal board
0-20 mA analog input	1	On on-board terminal board
Analog outputs +/-10V, - DAC 16 bit	8	Expandable on FDC card
5 V Push Pull encoder interface	8	Expandable on FDC card
5V Line Driver encoder interface without index inputs (encoder # 9)	1	On on-board terminal board
Digital 24V PNP inputs i28 & i29	2	On request, as alternative to encoder # 9
Absolute encoder interfaces	for 8/16 SSI encoder	On optional SF80328 card
STEP / DIRECTION outputs	for 8/16 axes	On optional T15-GENFR5 card
PWM Outputs	for 8 axes	+ 8 optional on FDC card
RS 232 serial port	2	On request, 1 can be RS485
CANopen fieldbus port	3	CiA standard Profile 401, 402 and 406
EtherCAT fieldbus port	1	Optional with CoE, EoE end FoE protocols
Mechatrolink II fieldbus port	1	On optional INT-Mechatrolink card
Ethernet port 10-100 T	1	TCP/IP, FTP, ModbusTCP and WEB server
USB port	2	
SPI interface	1	On 20 pins flat cable connector
LVDS interface	1	Optional:  on 26 pin conn. for obsolete active remote terminals  on 36 pin conn. for remote terminals
Relay safety outputs	1	
Power supply	24 Vdc	







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## **Warnings**

Before powering up the controller you should always check the following:

- 1. That the power is supplied only via terminal M1
- 2. That the supply voltage never exceeds 27 VDC
- 3. That the connections between the + and of the power supplies are not reversed, both incoming or exiting the controller
- 4. That the encoders are not fed with voltages other than those provided by the controller
- 5. That the position of connectors having the same number of poles have not been inverted



Failure to observe any of these recommendations could cause irreparable damage to the controller.

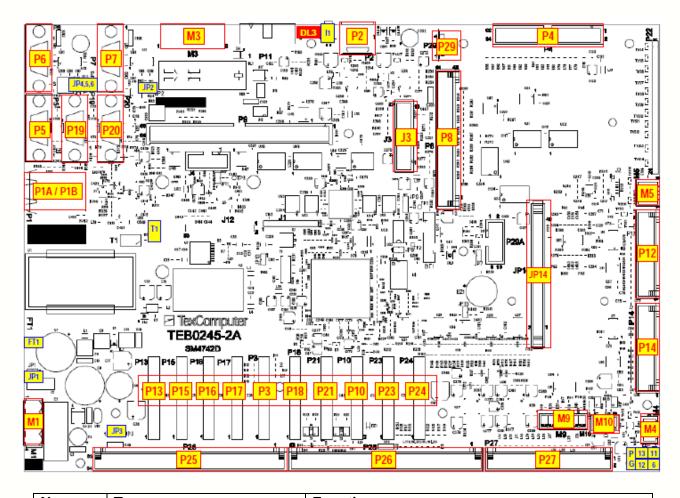




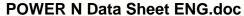
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Name	Type	Function	
P1A *	Bottom RJ5 connector	EtherCAT (activation as option)	
P1B *	Top RJ45 connector	Ethernet 10/100 T	
P2	USB connector	USB port # 2	
P5	9 pin D connector	CAN A (0-63 addressable nodes)	
P6	9 pin D connector	COM 1 RS232 (RS485 optional)	
P7	9 pin D connector	COM 2 RS232	
P8	40 pin flat connector	Connection to FDC expansion card	
P10	Connector for I / O module	Set with 8 points digital input or output	
P12	26 pin flat connector	PWM and axes U, V, A and C DIR outputs	
		4 Analog inputs 0-10V / 0-2mA at 12 bit	
P14	26 pin flat connector	PWM and axes X, Y, Z and W DIR outputs	
		4 Analog inputs 0-10 V / 0-5V at 12 bit set by PG6, 11,	
		12 and 13 (0-10V as default)	
P19	9 pin D connector	CAN B (64-127 addressable nodes) + VA power supply	
P20	9 pin D connector	CAN C (128-191 addressable nodes)	
P25	64 pin flat connector	31 Digital inputs (also for use as Home limit switch)	
		6 Configurable digital inputs / outputs	
		16 Digital outputs	





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Name	Туре	Function
P26	64 pin flat connector	A, B and Z signals, encoders # 1, 2, 3 and 4
		Analog outputs +/- 10 V # 1, 2, 3 and 4
		Digital outputs, enabling of axes # 1, 2, 3 and 4
		1 Emergency input
		16 Digital inputs (also for use as Home limit switch)
		2 Configurable digital inputs / outputs
		9 Digital outputs
P27	40 pin flat connector	A, B and Z signals, encoders # 5, 6, 7 and 8
		Analog outputs +/- 10 V # 5, 6, 7 and 8
		Digital outputs, enabling of axes # 5, 6, 7 and 8
		3 Digital outputs
Doo	LIOD	4 Digital inputs (also for use as Home limit switch)
P29	USB connector	USB port # 1
M1	4 pin terminal board	Controller and I/O power supply
M3	8 pin terminal board	OMRON G78A-2A2B safety relay contacts
M4	3 pin terminal board	Analog input +/- 10V + input 0-20mA – 12 bit
M5	6 pin terminal board,	3 Analog inputs 0-5 Volt at 12 bit
M9 **	6-pin Terminal board	A, B signals encoder #9 - 5V Line Driver (5V Push Pull
N440 **	clamp. Spring	on request)
M10 **	3 pin terminal board	Digital inputs i28 & i29, 24V PNP, alternative to encoder # 9
J3	20 pin flat connector	SPI interface for internal optional card
PG2	Spot welding	Change the analog input ADC (5) FS to 0-20mA
PG3	Spot welding	Change the analog input ADC (4) FS to 0-20mA
PG4	Spot welding	Change the analog input ADC (35) FS to 0-20mA
PG5	Spot welding	Change the analog input ADC (36) FS to 0-20mA
PG6	Spot welding	Decreases the analog input ADC (3) FS at 5V
PG11	Spot welding	Decreases the analog input ADC (2) FS at 5V
PG12	Spot welding	Decreases the analog input ADC (1) FS at 5V
PG13	Spot welding	Decreases the analog input ADC (0) FS at 5V
JP1	Jumper	Short-circuiting of logic GND and analog GND
JP2	Jumper	RS485 port termination resistor
JP4	Jumper	CAN A port termination resistor
JP5	Jumper	CAN B port termination resistor
JP6	Jumper	CAN C port termination resistor
FT1	Faston	2,5 mm <sup>2</sup> cable earth connection
I1	Micro-pushbutton	Start of Boot function

<sup>\*</sup> The Ethernet connectors are mounted horizontally and stacked, so when the Box versions are installed a gap of about 5 cm should be left on this side of the controller.



<sup>\*\*</sup> The connectors M9 and M10 are alternatives to each other; M10 connector must be requested when ordering.



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## For connectors without numbering, pin 1 is highlighted in red.

M1 TERMINAL BOARD (power supply)

Terminal	Function
1	VA +24 Vdc Controller and I/O power supply
2	GNDA 0Vdc power supply
3	GNDA 0Vdc power supply
4	VA +24 Vdc Controller and I/O power supply

M3 TERMINAL BOARD (safety relay)

Terminal	Function
1	K1A-NA1 safety relay NO contact (normally open contact of o40)
2	K1A-NA2 safety relay NO contact (normally open contact of o40)
3	K1B-NA1 safety relay NO contact (normally open contact of o40)
4	K1B-NA2 safety relay NO contact (normally open contact of o40)
5	K1A-NC1 safety relay NC contact (normally closed contact of o40)
6	K1A-NC2 safety relay NC contact (normally closed contact of o40)
7	K1B-NC1 safety relay NC contact (normally closed contact of o40)
8	K1B-NC2 safety relay NC contact (normally closed contact of o40)

The internal relay K1, which can be activated by output o40, is an TE CONNECTIVITY SR4D4024 safety relay with two pairs of forced-guide contacts called K1A and K1B. Redundancy is obtained by connecting the 2 NO contacts in series with each other and the 2 NC contacts in parallel. The relay K1 is powered by the voltage VA through an internal electronic circuit.

M4 TERMINAL BOARD (+/- 10V and 0-20 mA input)

Terminal	Function
1	+/- 10 V Analog input readable with ADC(32) operator, range 164014744, res12 bit
2	GND
3	0-20 mA Analog input readable with ADC(27) c operator, range 0 16384, resolut.12 bit

M5 TERMINAL BOARD (3 analog inputs at 5V)

Morsetto	Funzione	Layout
1	Analog GND	
2	5 V Analogue input readable with ADC(256) operator	
3	5 V Analogue input readable with ADC(257) operator	
4	5 V Analogue input readable with ADC(258) operator	
5	Analog GND	
6	+ 5V for potentiometer power supply	5 6

M9 TERMINAL BOARD (encoder # 9, as alternative to M10)

Terminal	Function	Note
1	CLK A channel A straight encoder # 9 / input i28 *	5V Line Driver or
2	CLK/ A channel A negated encoder # 9	Push Pull **
3	CLK B channel B straight encoder # 9 / input i29 *	5V Line Driver or
4	CLK/B channel B negated encoder # 9	Push Pull **
5	GND power supply ground encoder #9	
6	VDC +5Vdc power supply for encoder #9	

<sup>\*</sup> The hardware configuration parameter "EMIOS30 function" allows you to use pin 1 & 3 as encoder inputs (the default) or as user inputs i28 & i29.





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\*\* On request, encoder's inputs can be supplied in 5V Push-Pull configuration; in this case the input signals must be connected to the straight channels and the negated channels must be left disconnected.

The encoder inputs can be filtered by software acting on Info 1623 and Info 1648.

## M10 TERMINAL BOARD (24V PNP inputs, as alternative to M9)

Morsetto	Funzione	
1	User input i28N - 24V PNP, inverted logic (1 to 0 V, 0 to 24V)	
2	24 VA +24 Vdc Controller and I/O power supply	
3	User input i29N - 24V PNP, inverted logic (1 to 0 V, 0 to 24V)	

These inputs must be enabled through "EMIOS30 function" Hardware configuration parameter.



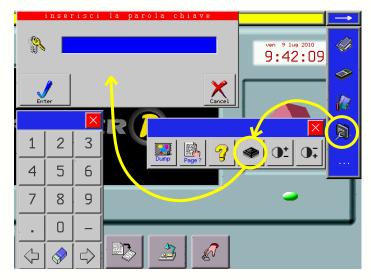
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#### **Ethernet Connection**

There is one parameter to enable Ethernet connection, one to set its IP address and one to declare its subnet mask; the first and the third one are accessible in the machine parameters, while the Ethernet address is in the "change card parameters" list accessible from the Boot menu (see also "Basic touch screen functions" in this data sheet). If the controller does not have a full hardware keyboard, the Boot menu should be accessed through the touch screen tool bar (remember that this access is protected by a password):



For further information, refer to the "User interface" section of the html manual. By default, the connection is already enabled and the controller can be accessed at IP address 192.168.0.200, subnet mask 255.255.255.0; to make a direct connection to a PLC (peer to peer mode), use a crossover Ethernet cable with 8-pin RJ45 connectors.

#### **BOX Version**

A "keyboard + display" kit is available for temporary connection to the BOX version for access to all the diagnostic and parameter setting functions only accessible by means of the HMI base of the Operating System. To activate its operation, set the type of display of the kit connected (generally an 8.4" VGA display) by switching on the controller with the F6 + 1 keys held down.

After use, the kit can be removed, remember to set the screen type as BOX again by switching on the controller with keys F7 + 0 held down, or using the Smart Bios configuration program.

#### **Volatile RAM memory**

In order to use more than 16 interpolated axes you need more RAM; for this reason, from 2015, you can request the option to add to the controller 4 or 8 Mbytes of volatile static RAM, that resets at every power on.

This memory is dedicated to the following functions:

- As a buffer to hold the compiled PLC code, before the transfer in Flash
- As a buffer to hold the CNC queue of movements (Look-Haed function)
- As a buffer to contain any extra additional V variables

#### Names of axes

This hardware configuration parameter associates the names of the axes to the hardware resources on the motherboard. These resources can be identified per type and differ for a consecutive numbering (e.g. encoder # 1, encoder # 2, PWM # 5 etc.). In the default configuration, to the first 16 axes are assigned the following names: XYZWUABCDVEFGHIJ; these names can also be modified but must





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consist of only 1 letter. The position adopted by each letter, starting from 0, is the number with which the axis will be identified, if it is installed; therefore, the default is: X is the axis # 0, J is the axis # 15.

#### Installed axes

In order to install axis and make them operative, the axes must be entered in the specific hardware configuration parameter. It's possible to modify default allocations of the hardware sources working on the respective special parameters of each axis.

For example: installing axes X and Y and modifying the "encoder number" parameter of the "X axis special parameters" from the "default" value to value "4" transfers the X axis feedback from encoder # 1 to encoder # 4, while the Y axis feedback will remain the default correlation to # 2.

The freed resources (encoder # 1 in the example) can be used by other axes or managed through specific commands available in the programming language.

## Number of axes beyond 16

If the optional volatile RAM is available, this parameter specifies the number of axes that you want to add to the first 16 (min.1, max. 8). In this case the names of added axes must be declared in their "long name" parameter. Additional axes are assigned to the positions 16 to 23; those that are not enabled by this parameter will still be used as an encoder becouse a reduced set of their "special parameters" will be available for them.

#### Parameters to associate hardware resources to the axes

"PWM/DAC/freq output number": destination of the PID output of the axis (valid values from 1 to 24).

The output which controls the direction of the axis cannot be changed from the default setting.

## Management of the limit switches dedicated to the axes

Inputs with a preset function are associated by default to each axis installed:

- Zero Limit Switch, allows you to modify axis position at its deactivation or at reception of a pulse generated by the encoder through a "0 Notch" signal. The input must be controllable in interrupt mode.
- Minimum Limit Switch, when activated, it stops axis movement and switches to alarm status and
  prevents any movement towards lower position values. Input must remain active until the axis
  physical bottom limit is reached.
- Maximum Limit Switch, when activated, it stops axis movement and switches to alarm status and
  prevents any movement towards higher position values. Input must remain active until the axis
  physical top limit is reached.

Generally Zero Limit Switch can also simultaneously work as one of the two limit switches (minimum or maximum), therefore by default the Zero and Minimum Limit Switchs use the same input.

#### +/- 10V Analog input

To use correctly analog input connected to pin 1 of terminal M4, you have to execute linearization of the value read through ADC (32) opearator, considering that:

- an input value of -10V corresponds to a value of 1640 um
- an input value of 0V corresponds to a value of 8192 um
- an input value of +10V corresponds to a value of 14744 um

As the converter's resolution is 12 bit, the minimum change noticeable will be 1,5996 um



<sup>&</sup>quot;encoder number": velocity/position feedback of the axis (valid values from 1 to 24)

<sup>&</sup>quot;enabling output": output to enable the drive of the axis (any available user output is valid).

<sup>&</sup>quot;zero sensor": input to change the position of the axis (only interrupt inputs are valid)

<sup>&</sup>quot;minimum sensor": input to limit the minimum stroke of the axis (any available input is valid).

<sup>&</sup>quot;maximum sensor": input to limit the maximum stroke of the axis (any available input is valid).



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## Other analog inputs

All analog inputs read by the operator ADC (xx) must be linearized with respect to the value of full scale (FS) of the input taking into account that:

- an input value of 0 % FS corresponds to a value of 0 um
- an input value of 100% FS corresponds to a value of 16384 um

As the converter's resolution is 12 bit, the minimum change noticeable will be 4 um

#### 64-bit math libraries

The Power N as default is supplied with firmware provided with math libraries to perform calculations in floating point 32-bit .

However, there are some applications where it is often necessary to increase the accuracy of the calculations in order to ensure maximum accuracy in the generation of the trajectories of the axes; for these cases there is also a version of the firmware compiled with 64-bit math libraries.

Logically, in order to obtain greater precision in the calculations you need to keep busy longer the CPU on the same mathematical instructions resulting in decreased processing speed of the application program.

For more information please contact the technical staff of Tex Computer.







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## P25 CONNECTOR (Digital I/O)

Pin	DESCRIPTION	NOTES
		NOTES
1	GNDA I/O power supply ground	
2	VA +24 I/O power supply	
3	GNDA I/O power supply ground	
4	VA +24 I/O power supply	
5	RUN CNC runs the last program executed by	User input i36
	the CNC	
6	HOLD blocks axis movement	User input i38
7	RUN PLC activates the PLC program	User input i37
8	User input i39	Axis # 9 (B) home limit switch
9	User output o0	
10	User input i0	
11	User output o1	
12	User input i1	
13	User output o2	
14	User input i2	
15	User output o3	
16	User input i3	
17	User output o4	
18	User input i4	
19	User output o5	
20	User input i5	
21	User output o6	
22	User input i6	
23	User output o7	
24	User input i7	
25	User output o8	
26	User input i8	Non usabile in interrupt
27	User output o9	·
28	User input i9	Non usabile in interrupt
29	User output o10	,
30	User input i10	Non usabile in interrupt
31	User output o11	,
32	User input i11	Non usabile in interrupt
33	User output o12	1 "
34	User input i12	Non usabile in interrupt
35	User output o13	
36	User input i13	Non usabile in interrupt
37	User output o14	
38	User input i14	Non usabile in interrupt
39	User output o15	
40	User input i15	Non usabile in interrupt
41	VA +24 I/O power supply	sodono ni mioriapi
42	User input i16	
43	VA +24 I/O power supply	
44	User input i17	
45	GNDA I/O power supply ground	
46	User input i18	
47	GNDA I/O power supply ground	
47	ONDA 1/O power suppry ground	





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Pin	DESCRIPTION	NOTES
48	User input i19	
49	GNDA I/O power supply ground	
50	User input i20	
51	User input i33	
52	User input i21	
53	User input i34	
54	User input i23	
55	User input i35	
56	User input i22	
57	User input i50 / User output o50 *	if input, it's Axis # 6 (V) home limit switch
58	User input i51 / User output o51 *	
59	User input i52 / User output 052 *	if input, it's Axis # 7 (A) home limit switch
60	User input i53 / User output o53 *	
61	User input i54 / User output 054 *	if input, it's Axis # 8 (C) home limit switch
62	User input i55 / User output o55 *	
63	GNDA I/O power supply ground	
64	VA +24 I/O power supply	

<sup>\*</sup> Depends on the I/O module inserted in slot P10





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## P26 CONNECTOR (axes 1-4 and digital I/O)

Pin	DESCRIPTION (AXES	NOTES
1	GNDANAL X X axis analog ground	10120
2	VREF X reference signal, +/- 10V	axis # 1
3	GNDANAL Y Y axis analog ground	
4	VREF Y reference signal, +/- 10V	axis # 2
5	GNDANAL Z Z axis analog ground	and # 2
6	VREF Z reference signal, +/- 10V	axis # 3
7	GNDANAL W W axis analog ground	uxio n o
8	VREF W reference signal, +/- 10V	axis # 4
9	GND logic ground for connection to screen	unio n +
10	GND logic ground for connection to screen	
11	CLKA X encoder # 1 channel	
12	CLKB X encoder # 1 channel	
13	NOTCH 0 X 0 channel encoder # 1	User input i56 only non optoinsulated IPT, 5V
14	GND logic ground for encoder power supply	Coor in partice of my from option localistic in 11, 01
15	CLKA Y encoder # 2 channel	
16	CLKB Y encoder # 2 channel	
17	NOTCH 0 Y 0 channel encoder # 2	User input i57 only non optoinsulated IPT, 5V
18	GND logic ground for encoder power supply	Coor in parties of my from option localization in 1; or
19	CLKA Z encoder # 3 channel	
20	CLKB Z encoder # 3 channel	
21	NOTCH 0 Z 0 channel encoder # 3	User input i58 only non optoinsulated IPT, 5V
22	GND logic ground for encoder power supply	l
23	CLKB W encoder # 4 channel	
24	CLKB W encoder #4 channel	
25	NOTCH 0 W 0 channel encoder # 4	User input i59 only non optoinsulated IPT, 5V
26	GND logic ground for encoder power supply	
27	VDC +5Vdc power supply for encoder	
28	VDC +5Vdc power supply for encoder	
29	VDC +5Vdc power supply for encoder	
30	VDC +5Vdc power supply for encoder	
31	User output o16	By default ENBX enabling of driver # 1
32	VA +24 I/O power supply	
33	User output o17	By default ENBY enabling of driver # 2
34	SELPNP/NPN	Note 1
35	User output o18	By default ENBZ enabling of driver # 3
36	GNDA I/O power supply ground	
37	User output o19	By default ENBW enabling of driver # 4
38	GNDA I/O power supply ground	
39	User input i46	By default Axis # 4 (W) zero limit stop
40	User input i40	By default Axis # 1 (X) zero limit stop
41	FCEMG emergency, Machine Running	s23, if EMG is deactivated becomes user input i47
42	User input i41	By default Axis # 1 (X) max limit stop
43	User output o32	Can become DIRO X axis # 1 direction output if "drive type" parameter = 2 or 4
44	User input i42	By default Axis # 2 (Y) home limit stop
45	User output o33	Can become DIRO Y axis # 2 direction output if "drive type" parameter = 2 or 4
46	User input i43	By default Axis # 2 (Y) max limit stop
.0	1 0001 input i io	by doladit 7 Mo II Z (1) Max III III Stop





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Pin	DESCRIPTION	NOTES
47	User output o34	Can become DIRO Z axis # 3 direction output
41	Oser output 034	if "drive type" parameter = 2 or 4
48	User input i44	By default Axis # 3 (Z) home limit stop
49	User output o35	Can become DIRO W axis # 4 direction output
	·	if "drive type" parameter = 2 or 4
50	User input i45	By default Axis # 3 (Z) max limit stop
51	VA +24 I/O power supply	
52	GNDA I/O power supply ground	
53	User input i48 / User output o48 *	if input, it's Axis # 5 (U) home limit stop
54	User input i49 / User output 049 *	
55	User input i32	
56	GNDA I/O power supply ground	
57	User input i25 **	Axis # 10 (D) home limit switch
58	User input i24 **	Not usable in interrupt mode
59	User input i26 **	By default Axis # 11 (E) home limit switch
60	User input i27 **	By default Axis # 12 (F) home limit switch
61	GNDA I/O power supply ground	
62	VA +24 I/O power supply	
63	User output o39	Can become DIRO C axis # 8 direction output
	Oddi odipat odd	if "drive type" parameter = 2 or 4
64		

<sup>\*</sup> Depends on the I/O module inserted in slot P10

**Note 1** this PIN polarises all inputs called "User input": if connected to VA it sets them as NPN, or if connected to GNDA it sets them as PNP.

Encoder inputs are CMOS type RC filter at input.

Logic level 0 of the encoder signal must be less than 1 Volt; logic level 1 must be higher than 4 Volts. If the frequency is higher than 250Khz use of the LINE-DRIVER interface is recommended.

The GNDANAL signals must be connect to the differential input of the drive, if they have one. If this is not the case the GNDANAL input signal must be free.

In this case, the GND is used as common reference signal between POWER N and DRIVE.

In the case of DRIVES without differential input, it might be necessary to connect the screened cable to ground at both ends or to connect the -vref signal of the drive directly to ground in the gnd drive. It depends on the specifications of drive and on how the control panel is constructed.



<sup>\*\*</sup> It is recommended to use these resources only after you have used all those available in the removable I/O modules.





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## P27 CONNECTOR (axes 5-8)

Pin	DESCRIPTION	NOTES
1	U axis GNDANAL	
2	VREF U reference signal, +/- 10V	axis # 5
3	V axis GNDANAL	
4	VREF V reference signal, +/- 10V	axis # 6
5	GND	
6	User output o20	By default ENBU enabling of driver # 5
7	User output o21	By default ENBV enabling of driver # 6
8	GNDA	
9	+VDC +5V for encoder power supply	
10	CLKA U encoder #5 channel	
11	GND encoder logic ground	
12	CLKb U encoder # 5 channel	
13	GND encoder logic ground	
14	NOTCH 0 U 0 channel encoder # 5	User input i60 only non optoinsulated IPT, 5V
15	+VDC +5Volt ENCODER	
16	CLKA V encoder #6 channel	
17	GND encoder logic ground	
18	CLKB V encoder #6 channel	
19	G N D encoder logic ground	
20	NOTCH 0 V 0 channel encoder # 6	User input i61 only non optoinsulated IPT, 5V
21	+VDC +5Volt ENCODER	
22	CLKA encoder #7 channel	
23	GND encoder logic ground	
24	CLKB encoder #7 channel	
25	GND encoder logic ground	
26	NOTCH 0 A 0 channel encoder # 7	User input i62 only non optoinsulated IPT, 5V
27	+VDC +5Volt ENCODER	
28	CLKA encoder #8 channel	
29	CLKB encoder #8 channel	
30	NOTCH 0 0 channel encoder # 8	User input i63 only non optoinsulated IPT, 5V
31	A axis GNDANAL	
32	A axis VREF	axis # 7
33	C axis GNDANAL	
34	C axis VREF	axis # 8
35	GND logic ground	
36	User output o22	By default ENBA enabling of driver # 7
37	User output o23	By default ENBC enabling of driver # 8
38	User output o36	Can become DIRO U axis # 5 direction output
		if "drive type" parameter = 2 or 4
39	User output o37	Can become DIRO V axis # 6 direction output
		if "drive type" parameter = 2 or 4
40	User output o38 XDIROA	Can become DIRO A axis # 7 direction output
		if "drive type" parameter = 2 or 4







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## P14 CONNECTOR (PWM # 1, 2, 3 and 4 + analog inputs)

Pin	DESCRIPTION	NOTES
1	VCC + 5Vdc power supply	
2	# 1 PWM control output for PWM drivers	
3	GND Logic Ground	
4	DIR # 1 output direction for PWM driver	User output o24 (5V TTL)
5	GND Logic Ground	
6	# 2 PWM control output for PWM drivers	
7	GND Logic Ground	
8	DIR # 2 output direction for PWM driver	User output o25 (5V TTL)
9	GND Logic Ground	
10	# 3 PWM control output for PWM drivers.	
11	GND Logic Ground	
12	DIR # 3 output for PWM driver	User output o26 (5V TTL)
13	+ 12/15 Volt DC 0.05A max	
14	# 4 PWM control output for PWM drivers.	
15	- 12/15 Volt DC 0.05A max	
16	DIR # 4 output direction for PWM driver	User output o27 (5V TTL)
17	ENABLE # 2 negated (0 = driver enabled)	User output o17 (O.C. max. 30V – 30mA)
18	ENABLE # 1 negated (0 = driver enabled)	User output o16 (O.C. max. 30V – 30mA)
19	ENABLE # 4 negated (0 = driver enabled)	User output o19 (O.C. max. 30V – 30mA)
20	ENABLE # 3 negated (0 = driver enabled)	User output o18 (O.C. max. 30V – 30mA))
21	VREF for analog inputs + 5Vdc	
22	AGND analog ground for analog inputs	
23	Analog input 1 – assignment to ADC (1)	Note 1 - 010V (05V if PG12 is closed)
24	Analog input 0 – assignment to ADC (0)	Note 1 - 010V (05V if PG13 is closed)
25	Analog input 3 – assignment to ADC (3)	Note 1 - 010V (05V if PG6 is closed)
26	Analog input 2 – assignment to ADC (2)	Note 1 - 010V (05V if PG11 is closed)
Mata		

#### Note 1:

The buffered analog inputs have a resolution of 12 bits; their input resistance is 200 Kohm (0..10V setting) or 100 Kohm (0..5V setting).







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## P12 CONNECTOR (PWM # 5, 6, 7 and 8 + analog inputs)

Pin	DESCRIPTION	NOTES
1	VCC + 5Vdc power supply	
2	PWM # 5 PWM driver command output	
3	GND logic ground	
4	DIR # 5 output direction for PWM driver	User output o28 (5V TTL)
5	GND logic ground	
6	PWM # 6 uscita comando per driver PWM	
7	GND logic ground	
8	DIR # 6 output direction for PWM driver	User output o29 (5V TTL)
9	GND logic ground	
10	PWM # 7 output command for PWM driver.	
11	GND logic ground	
12	DIR # 7 output direction for PWM driver	User output o30 (5V TTL)
13	+ 12/15 Volt DC 0.05A max	
14	PWM # 8 PWM driver command output	
15	- 12/15 Volt DC 0.05A max	
16	DIR # 8 output direction for PWM driver	User output o31 (5V TTL)
17	ENABLE # 6 negated (0 = driver enabled)	User output o21 (O.C. max. 30V – 30mA)
18	ENABLE # 5 negated (0 = driver enabled)	User output o20 (O.C. max. 30V – 30mA)
19	ENABLE # 8 negated (0 = driver enabled)	User output o23 (O.C. max. 30V – 30mA)
20	ENABLE # 7 negated (0 = driver enabled)	User output o22 (O.C. max. 30V – 30mA)
21	VREF for analog inputs + 5Vdc	
22	AGND analog ground for analog inputs	
23	Analog input 5 – assignment to ADC (5)	Note 2 - 010V (020mA if PG2 is closed)
24	Analog input 4 – assignment to ADC (4)	Note 2 - 010V (020mA if PG3 is closed)
25	Analog input 36 – assignment to ADC (36)	Note 2 - 010V (020mA if PG5 is closed)
26	Analog input 35 – assignment to ADC (35)	Note 2 - 010V (020mA if PG4 is closed)

## Note 2:

The analog inputs have a resolution of 12 bits and accept voltages between 0 and 10 volts. They are buffered to make their input resistance high; if settedin order to accept input signals to 0-20 mA their input resistance is 499 ohm.

<u>WARNING:</u> this document only describes the electrical connections of the connectors most often used. For all further information about electrical connections refer to the "Electrical Connections" section of the electronic document entitled "Power Family Controllers - USE AND PROGRAMMING MANUAL". The constantly updated version of this manual, supplied as a compiled HTML Help file called "Power Family.chm", can be downloaded from the "Download Service" area of the <a href="www.texcomputer.com">www.texcomputer.com</a> site.







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## **DIGITAL INPUTS (consecutive numbering)**

input	connector	pin	slot I/O	notes
i0	P25	10		
i1	P25	12		
i2	P25	14		
i3	P25	16	P13	
i4	P25	18	PIS	
i5	P25	20		
i6	P25	22		
i7	P25	24		
i8	P25	26		Not usable in interrupt mode
i9	P25	28		Not usable in interrupt mode
i10	P25	30		Not usable in interrupt mode
i11	P25	32	P15	Not usable in interrupt mode
i12	P25	34	1 10	Not usable in interrupt mode
i13	P25	36		Not usable in interrupt mode
i14	P25	38		Not usable in interrupt mode
i15	P25	40		Not usable in interrupt mode
i16	P25	42		
i17	P25	44		
i18	P25	46		
i19	P25	48	P16	
i20	P25	50	1 10	
i21	P25	52		
i22	P25	56		
i23	P25	54		
i24	P26	58		Not usable in interrupt mode
i25	P26	57		Not usable in interrupt mode
i26	P26	59	motherboard	
i27	P26	60		
i28N	M10	1		Digital inputs 24V PNP with inverted logic, as
i29N	M10	3		alternative to encoder # 9 (M9 connector)
i32	P26	55		
i33	P25	51		
i34	P25	53	D47	
i35	P25	55		
i36	P25	5	P17	RUN CNC (executes the selected CNC program)
i37	P25	7		RUN PLC (activates the PLC program; interrupt MDA)
i38	P25	6		HOLD (blocks axis movement)
i39	P25	8		





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input	connector	pin	slot I/O	notes
i40	P26	40		Axis # 1 (X) home limit switch
i41	P26	42		Axis # 1 (X) max limit switch
i42	P26	44		Axis # 2 (Y) home limit switch
i43	P26	46	P21	Axis # 2 (Y) max limit switch
i44	P26	48	PZ1	Axis # 3 (Z) home limit switch
i45	P26	50		Axis # 3 (Z) max limit switch
i46	P26	39		Axis # 4 (w) home limit switch
i47	P26	41		s23 emergency in. (if EMG is deactivated => i47)
i48 *	P26	53		Config. as o48* or Axis 5 (U) home limit switch
i49 *	P26	54		Configurable as o49*
i50 *	P25	57		Config. as o50* or Axis 6 (V) home limit switch
i51 *	P25	58	P10	Configurable as o51*
i52 *	P25	59	10	Config. as o52* or Axis 7 (A) home limit switch
i53 *	P25	60		Configurable as o53*
i54 *	P25	61		Config. as o54* or Axis 8 (C) home limit switch
i55 *	P25	62		Configurable as o55*
i56	P26	13		X axis 0 notch (5 V TTL, TPU interrupt)
i57	P26	17		Y axis 0 notch (5 V TTL, TPU interrupt)
i58	P26	21		Z axis 0 notch (5 V TTL, TPU interrupt)
i59	P26	25		W axis 0 notch (5 V TTL, TPU interrupt)
160	P27	14	motherboard	U axis 0 notch (5 V TTL, TPU interrupt)
<mark>i61</mark>	P27	20		V axis 0 notch (5 V TTL, TPU interrupt)
162	P27	26		A axis 0 notch (5 V TTL, TPU interrupt)
163	P27	30		C axis 0 notch (5 V TTL, TPU interrupt)
i88	-	-		Microswitch I1

<sup>\*</sup> Depends on the I/O module inserted in slot P10: if it's a digital input module the hardware configuration parameter ""direction I / O port user" must be set to 000000**0**0. WARNING: after this parameter is changed the PLC program must be recompiled



<sup>\*\*</sup> It is recommended to use these resources only after you have used all those available in the removable I/O modules.





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## **DIGITAL OUTPUTS (consecutive numbering)**

output	connector	pin	slot I/O	notes
00	P25	9		
01	P25	11		
o2	P25	13	P3	
03	P25	15		
04	P25	17		
05	P25	19		
06	P25	21	P3	
o7	P25	23		
08	P25	25		
09	P25	27		
o10	P25	29		
o11	P25	31	P18	
012	P25	33	PIO	
o13	P25	35		
014	P25	37		
o15	P25	39		
o16	P26	31		ENB # 1 (X) These outputs are available also
o17	P26	33	P23	ENB # 2 (Y) on P14 connector (5V TTL ); they
o18	P26	35	1 25	ENB # 3 (Z) can be used like ENB negated
o19	P26	37		ENB # 4 (W) for axes # 1, 2, 3 and 4.
o20	P27	6		ENB # 5 (U) These outputs are available also
o21	P27	7	P24	ENB # 6 (V) on P12 connector (5V TTL ); they
022	P27	36	124	can be used like ENB negated for axes # 5, 6, 7 and 8.
o23	P27	37		ENB # 8 (C)   101 axes # 5, 6, 7 and 6.
o24	P14	4		PWM DIR # 1 (X) (5V TTL)
o25	P14	8		PWM DIR # 2 (Y) (5V TTL)
o26	P14	12		PWM DIR # 3 (Z) (5V TTL)
o27	P14	16	motherboard	PWM DIR # 4 (W ) (5V TTL)
o28	P12	4	ouioibodid	PWM DIR # 5 (U) (5V TTL)
o29	P12	8		PWM DIR # 6 (V) (5V TTL)
o30	P12	12		PWM DIR # 7 (A) (5V TTL)
o31	P12	16		PWM DIR # 8 (C) (5V TTL)
o32	P26	43		DIRO X if drive # 1 type = 2 or 4
o33	P26	45	P23	DIRO Y if drive # 2 type = 2 or 4
o34	P26	47	P23	DIRO Z if drive # 3 type = 2 or 4
o35	P26	49		DIRO W if drive # 4 type = 2 or 4





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output	connector	pin	slot I/O	notes
036	P27	38		DIRO U if drive # 5 type = 2 or 4
037	P27	39	P24	DIRO V if drive # 6 type = 2 or 4
038	P27	40	F24	DIRO A if drive # 7 type = 2 or 4
o39	P26	63		DIRO C if drive # 8 type = 2 or 4
o40	М3	1&2 3&4 5&6 7&8		Control of safety relay OMRON G7SA-2A2B
o41	-	-	motherboard	Reserved for buzzer control
042	-	-		DL3 led management
o48 *	P26	53		Configurable as i48* or Axis 5 (U) home switch
o49 *	P26	54		Configurable as i49 *
o50 *	P25	57		Configurable as i50 *
o51 *	P25	58	P10	Configurable as i51 *
o52 *	P25	59	FIU	Configurable as i52 *
o53 *	P25	60		Configurable as i53 *
o54 *	P25	61		Configurable as i54 *
o55 *	P25	62		Configurable as i55 *

<sup>\*</sup> Depends on the I/O module inserted in slot P10 : if it's a digital output module the hardware configuration parameter ""direction I / O port user" must be set to 00000010.

WARNING: after this parameter is changed the PLC program must be recompiled

#### Power supply for outputs separate from VA

On slots P3, P10, P18, P23 and P24 are pluggable the output modules that, by default, are powered by the voltage VA which supplies the controller.

In each module there are a faston and a jumper: removing the jumper disconnects the faston from VA so that it can be used to apply to the module a different voltage supply.

The max. applicable voltage is 30 Vdc, with the positive on the faston, and the negative in common with the power supply of the controller (GNDA); the max. output current from each output is 1A, but the whole module must not supply more than 3A.



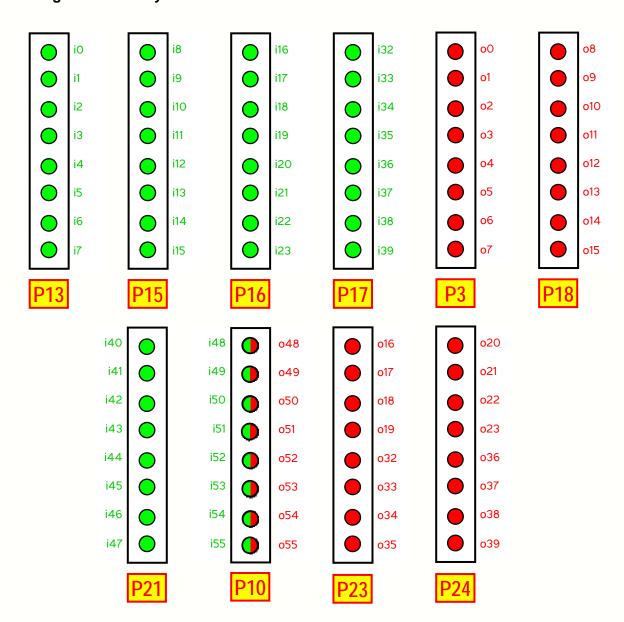


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## **Diagnostic LED layout**









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## **ANALOG INPUTS (consecutive numbering)**

input	connector	pin	full scale	notes
0		24		0-5V witn Pg13 close
1	P14	23	0-10V	0-5V witn Pg12 close
2	F 14	26	0-100	0-5V witn Pg11 close
3		25		0-5V witn Pg6 close
4	P12	P12 0-10V	0-20 mA on request	
5	P12	23	0-107	0-20 IIIA dii request
27	M4	3	0-20 mA	
32	1014	1	+/- 10V	
35	P12	26	0-10V	0-20 mA on request
36	P12	25	0-107	0-20 IIIA OII Tequest
256	M5	2		
257		3	0-5V	
258		4		

## **ANALOG OUTPUTS (consecutive numbering)**

output	connector	pin	full scale	notes
1		2		
2	Doe	4	+/- 10V	from DAC with 16 bits resolution
3	P26	6		
4		8		
5		2	+/- 10 V	HOITI DAC WILL TO DIES TESOIGLIOTI
6	P27	4		
7		32		
8		34		





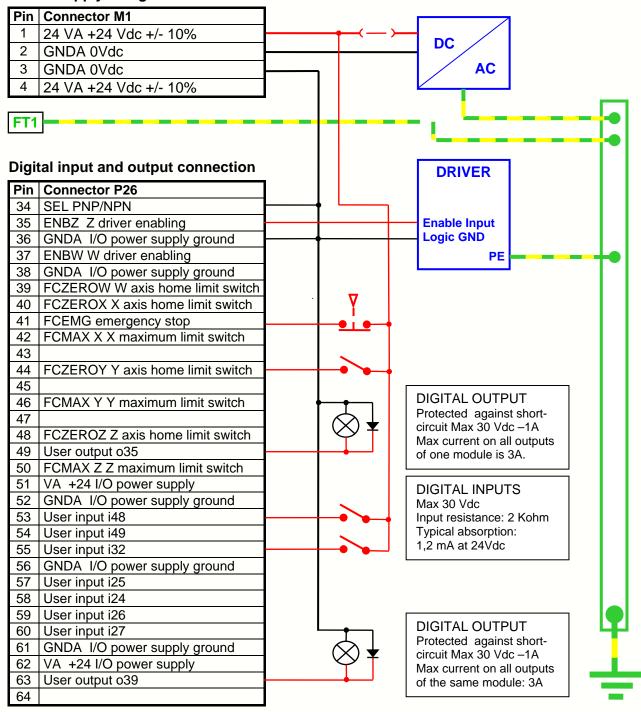


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#### CONNECTION EXAMPLES

This section is an extract of the information provided in the "Electrical Connections" section of the manual supplied with the controller, to which you must always refer for the wiring of the system according to the constructor's technical recommendations.

## Power supply and ground connection



**NB:** CE regulations recommended to place the free-wheeling diode in proximity of each inductive load to prevent the spread of electromagnetic interference along the wiring cables.

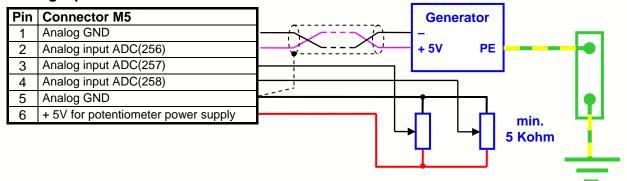




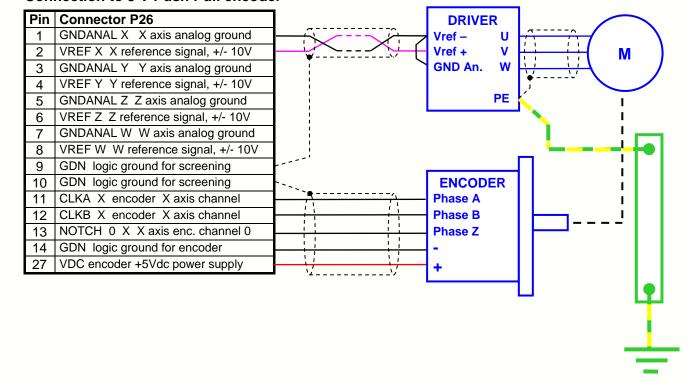


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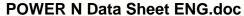
## **Analog input connection**



#### Connection to 5 V Push Pull encoder





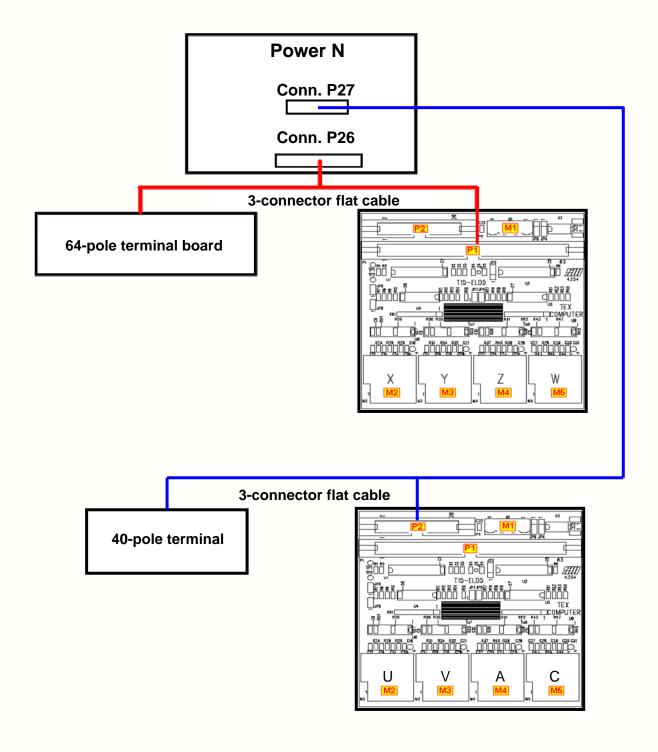




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#### Connection to 5V Line Driver encoder

An interface card called **T15ELD** must be added to connect encoders with Line Driver type output to the controller. This interface must be connected with a 3-connector flat cable which makes all the necessary electrical connections available on 4 different terminal boards, called **M2**, **M3**, **M4** and **M5**. If T15ELD is connect to the Driver's "simulated encoder" you don't have to connect + 5Vdc terminal.





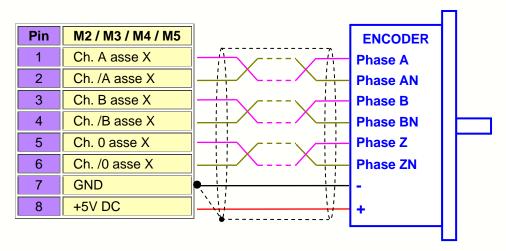




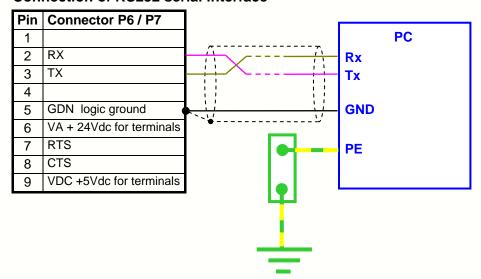
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#### **T15ELD interface connections**

The connections must be made by means of twisted screened cable. If the "simulated encoder" outputs generated by the driver are connected to the T15ELD interface instead of the encoder, the + 5Vdc terminal is not connected.



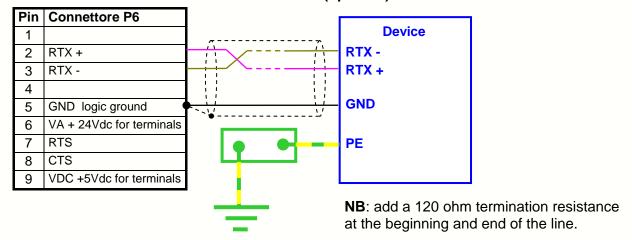
#### Connection of RS232 serial interface





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## Connection of RS485 serial interface COM 1 (optional)



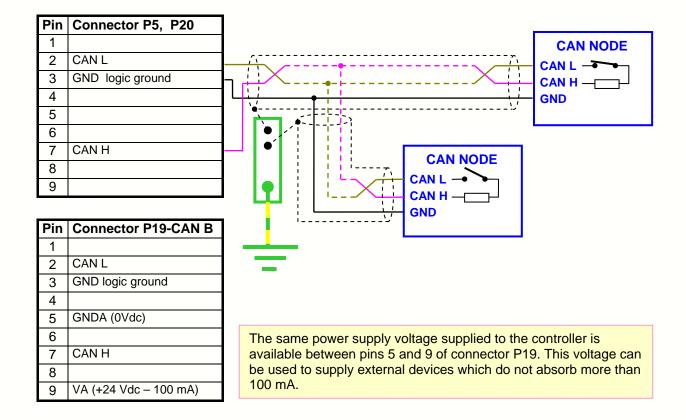
## **CANopen interface connection**

The Power N is able to control up to 3 CAN ports using both the CiA 301 general communication protocol and the specific profiles CiA 401 (I/O devices), CiA 402 (drives) and CiA 406 (encoder).

Be careful not to use in the same network devices CiA 401 and CiA 402 because it could result in a malfunction.

The CAN network must be done with twisted screened cables and the furthest ends of CAN H and CAN L signals must be charged through a 120 ohm termination resistance.

In the Power N, the termination resistances are already connected by default and can be disconnected by removing jumpers JP4 (P5), JP5 (P19) and JP6 (P20), but you have to install the termination resistance at the other end of the network.







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#### Connection to an active remote Panel

If the Power N BOX is equipped with an optional graphics card with LVDS (Low Voltage Differential Signaling) interface, you can connect to the controller, up to a maximum distance of 10 m, any front Panel complete with display, touch screen, keyboard and USB port.

On board of the active remote panel must be present the intelligent card TRM-003 which manages, through its own microprocessor, the keyboards with 16, 28, 56, 75 or 80 keys (for this last with the exclusion of the vertical keys from A4 to A8).

The keys and the local I/O of the card are encoded and transmitted via RS232 to the controller, which takes care of the direct management of LCD, touch screen and USB port using the signals present in the LVDS cable.

Through the same LVSD cable the electrical contacts ,relative to an emergency button and to a "dead man" safety button, can be transferred on the M6 terminal of the controller.

The serial port used is the COM 2 (P7 connector of the controller) on which you will find, already inserted, a connector with the cable to link it with the graphics card; to function properly, the communication must be set with the following parameters:

baud rate: 57600

parity = N

format: 8 bit data + 1 bit stop

<u>IMPORTANT:</u> the remote panel chassis must be connected to ground by means of a cable with gauge of at least 2.5 mm2.

#### Connection to 8.4" active mobile terminal

Since March 2016 the active 8.4 "mobile terminal is equipped with smart card TRM-003 and therefore are valid the considerations done in the previous paragraph.

On board there is the M1 connector, which supports the following electrical connections:

Pin	M1 terminal board
1	1 EMG CONTACT (N.C.)
2	2 EMG CONTACT (N.C.)
3	1 & 2 EMG CONTACT (Common)
4	VA terminal power supply, coming from LVDS cable
5	Dead man CONTACT
6	
7	GND
8	GND
9	
10	GND

The logic states of the **key-switch** and **buzzer** installed on the mobile terminal are visible from the application program through system's parameters:

s331: key-switch s332: buzzer

For more information refer to TRM-003 data sheet.





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#### Basic functions of the touch screen

**FUNZIONI DI BOOT** 

F3 = full ram clear

F4 = reset F5 = load file F6 = clear screen

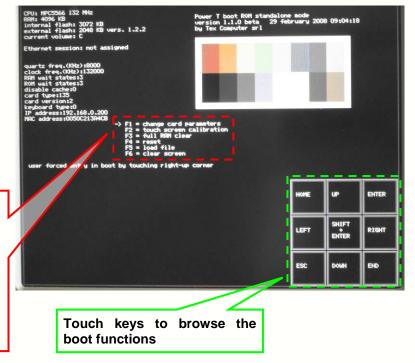
F1 = change card parameter F2 = touch screen calibration

F7 = save current firmware

F8 = export card parameter

On the controllers equipped with touch screen, a number of basic functions can be accessed immediately without having to enable and calibrate the screen.

 If at start up the system detects pressure in the <u>top right-hand</u> corner of the screen, it accesses the Boot menu:



WARNING: the Boot menu only manages the USB memories and not any other peripherals, such as the keypad and the mouse, which may be connected to the same USB port by means of a hub.

Once you are in Boot menu, we suggest you to calibrate the touch screen so that the touch function is still active when the system is switched on again, even after running functions F3 and F4 which partially or totally clear the RAM memory.

We recommend not to alter the card's basic configurations without contacting first the Tex Computer's technical staff.

 If at start up the system detects a pressure at the top left-hand corner of the screen you enter the menu which allows the operator to disable some functions during the current start-up phase. The following check list will be displayed:

Touching the screen on each of the white boxes allows the user to check or un-check the functions to be disabled during the current start-up phase. Pressing ENTER you confirm the selections made, which affect the current start-up phase only and not the following ones

For further information about the functions of the touch screen, refer to the manual with the same name.

Disable on s	startup
Autostart CNC	
<b>✓</b> PLC	
Alias	
CANOpen	
Ethernet	
	Select All
Enter	Cancel







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## Power N 10.4" XGA with electronic handwheel

In this version, the controller is supplied equipped with the optional INT-CFC-USB1 card fitted behind the front door which gives access to the Ethernet port, the USB slot and the CF removable memory connector.

The following resources are electrically connected to the INT-CFC-USB1 card and terminal board M5:

Name	Typical function with ISO program	Resource
Electronic Handwheel	100 ppr incremental encoder which can be used to move the axis selected with the axis selector in electric shaft mode.	Encoder # 9
Axis selector	Allows selection of the axis to be linked to the control knob in electric shaft mode; just one input will be active corresponding to the letter shown. In OFF position, no inputs are active.	i224 (X axis) i225 (Y axis) i226 (Z axis) i227 (A axis) i228 (B axis) i229 (C axis)
Numerical selector knob	Can be used to change the resolution of electric shaft movement of the axis connected to the electronic handwheel	i232 (setting 1) i233 (setting 2) i234 (setting 3) i235 (setting 4)
Axis overfeed	Regulates the axis feed speed	ADC(256) *
Spindle Overfeed	Regulates the spindle rotation speed	ADC(257) *

<sup>\*</sup> Analog inputs on terminal board M5



To enable operation of card INT-CFC-USB1 the "has a INT-FDC-CFC-USB" parameter must be set as "yes".

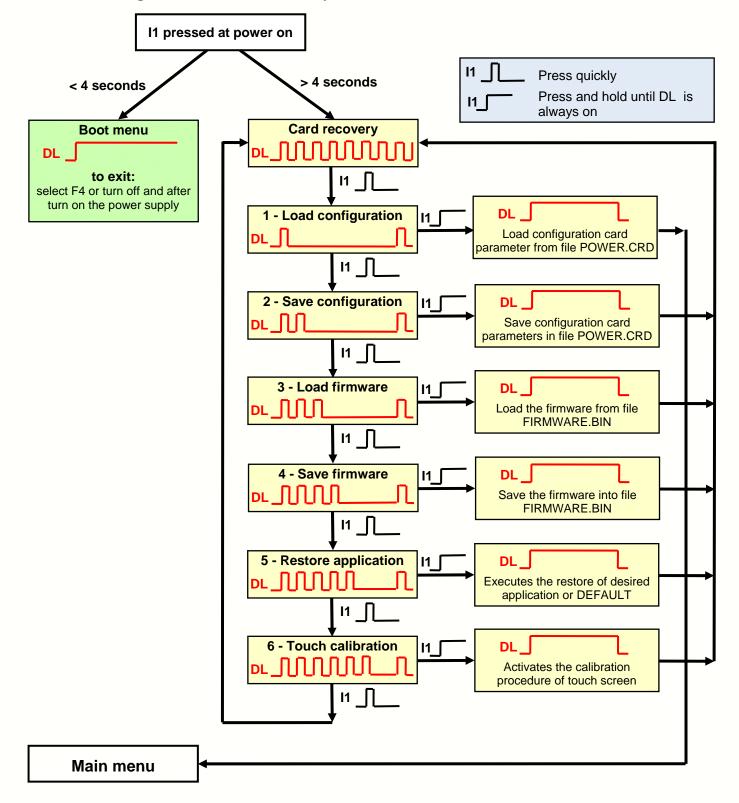






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## **Recalling Boot and Card recovery Functions from I1**







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The controller is equipped with a microswitch, called I1, located on one side of the motherboard; next to it there is also a red LED DL3. Pressing the microswitch I1 at power on you can access both the **Boot menu** and the **Card recovery** functions which allow you to upload from a removable storage device, a text file, called POWER.CRD, where there are listed the values of the main card configuration parameters, including the IP address of the controller; these features are particularly useful for Box version controllers.

Starting from firmware 1.4.2 & boot 1.6.3 the following functions have been added:

- 3 Load firmware can load indifferently both the Main and the Boot of the controller if ,in the storage medium , they are called FIRMWARE.BIN.
- 5 Restore application with which you can activate the procedure that allows you to instantly
  load the backup of an application program, present on the main root of a removable storage
  drive, whose name is defined in the operator parameter Restore at reset. If this parameter is
  empty it will be automatically searched for an application program called DEFAULT
- 6 Touch calibration that gives you instant access to the calibration of the touch screen

You can exit the Card recovery menu at any time by turning off and on the power supply of controller.





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## Interchangeability with Power M

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Power N has been designed in such a way as to make possible to increase the performance of machines equipped with Power M by making only minor modifications to the electrical wiring and to the program.

The table shows the changes needed to achieve interchangeability:

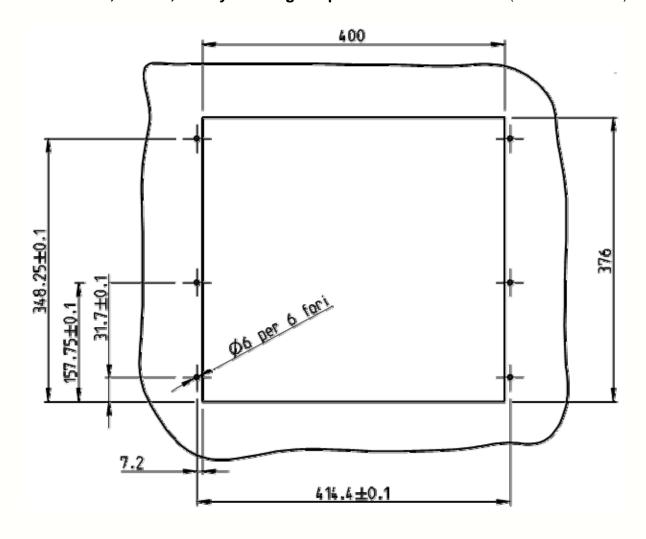
Description	Power M	Power N	Interchangeability
M1 - Pin 4 - power supply	VAX	VA	only if the JP2 on Power M is closed (default)
M3 - Pin 7 - safety power supply	VAY	-	none
M3 - Pin 8 - safety output	OUTK2	-	none
<b>M5</b> - Pin 2 - 0-5V analog in	ADC(37)	ADC(256)	with software modification
<b>M5</b> - Pin 3 - 0-5V analog in	ADC(38)	ADC(257)	with software modification
<b>M5</b> - Pin 4 - 0-5V analog in	ADC(34)	ADC(258)	with software modification
M6 - Safety circuit	optional	-	none
<b>P12</b> - Pins 23, 24,25 e 26 - analog inputs	010V trimmerable	010V (default) 05V (welding spot closed)	with trimmer set to 5V or 10V (default); in all other cases it is necessary to modify the application program.





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## Power N 10,4" XGA, 80 keys drilling template

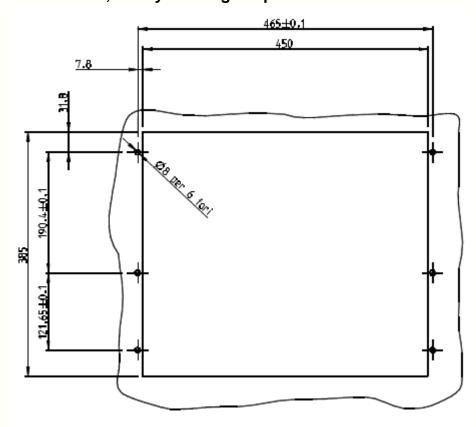






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## Power N 15", 80 keys drilling template

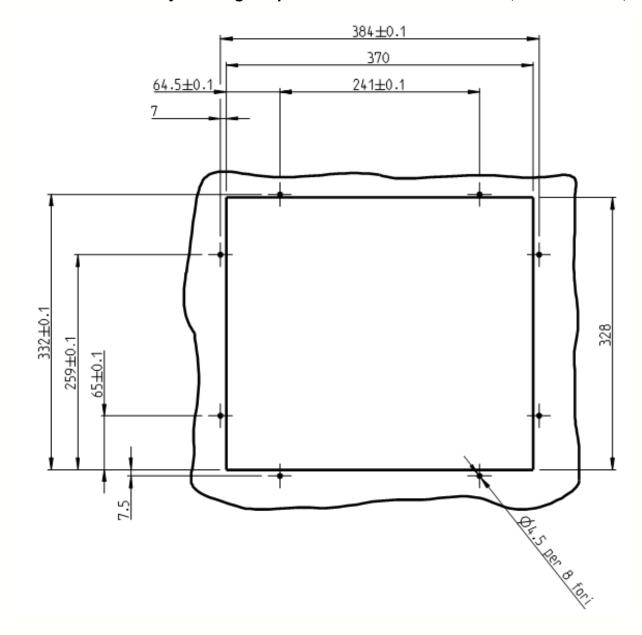






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## Power N 15" - 28 keys drilling template



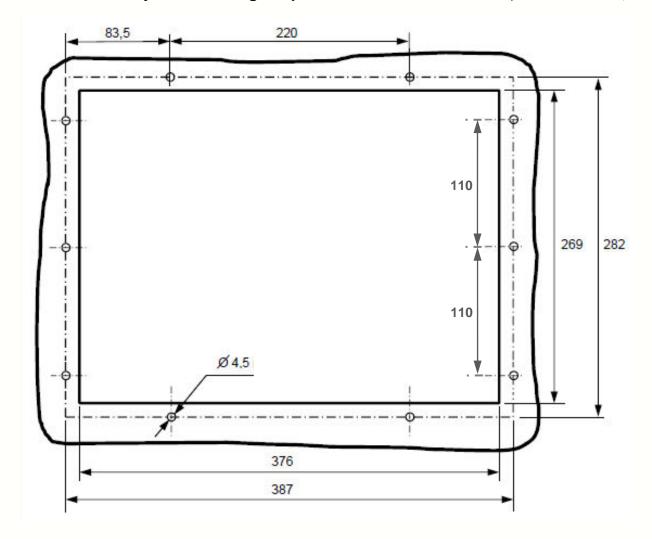






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## Power N 15" only touch drilling template







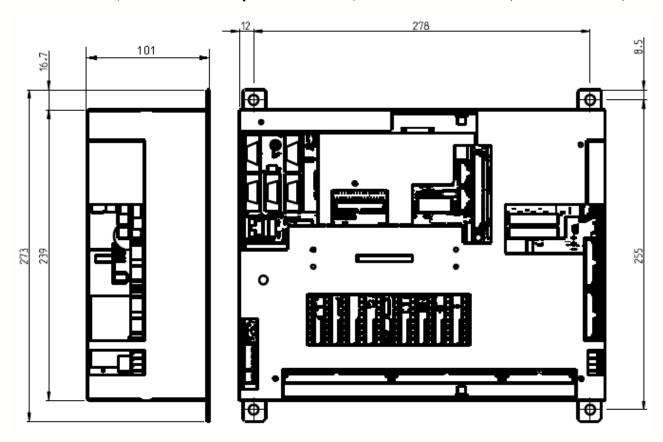
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## Power N Box, without FDC expansion board, dimensions

(Dimensions in mm)



With FDC expansion board the overall height is 160 mm.

For the mounting hole positions and dimensions of other versions, refer to the Power Family html manual.

Data subject to modification without notice

